# **RESUMEN DE TESIS DOCTORAL**

# **Restricted Conceptual Clustering Algorithms based on Seeds**

Algoritmos Conceptuales Restringidos basados en Semillas

### Graduated: Irene Olaya Ayaquica Martínez

National Institute of Astrophysics, Optics and Electronics Luis Enrique Erro # 1, Santa María Tonantzintla, C.P. 72840, Puebla, México. <u>Graduated in July 19, 2007</u>

#### Advisor: José Francisco Martínez Trinidad

National Institute of Astrophysics, Optics and Electronics Luis Enrique Erro # 1, Santa María Tonantzintla, C.P. 72840, Puebla, México. fmartine@inaoep.mx

### Advisor: Jesús Ariel Carrasco Ochoa

National Institute of Astrophysics, Optics and Electronics Luis Enrique Erro # 1, Santa María Tonantzintla, C.P. 72840, Puebla, México. ariel@inaoep.mx

### Abstract

The non-supervised classification algorithms determine clusters such that objects in the same cluster are similar among them, while objects in different clusters are less similar. However, there are some practical problems where, besides determining the clusters, the properties that characterize them are required. This problem is known as conceptual clustering.

There are different methods that allow to solve the conceptual clustering problem, one of them is the conceptual kmeans algorithm, which is a conceptual version of the k-means algorithm; one of the most studied and used algorithms for solving the restricted non-supervised classification problem (when the number of clusters is specified *a priori*). The main characteristic of the conceptual k-means algorithm is that it requires generalization lattices for the construction of the concepts. In this thesis, an improvement of the conceptual k-means algorithm and a new conceptual k-means algorithm that does not depend on generalization lattices for building the concepts are proposed.

Finally, in this thesis, two fuzzy conceptual clustering algorithms, which are fuzzy versions of the proposed hard conceptual clustering algorithms, are introduced.

Keywords: Conceptual Clustering, Fuzzy Conceptual Clustering, Similarity Functions, Mixed Data.

### Resumen

El estudio de la clasificación no supervisada ha sido enfocado principalmente a desarrollar métodos que determinen agrupamientos tales que objetos en el mismo agrupamiento sean similares entre ellos, mientras que objetos de diferentes agrupamientos sean poco similares. Sin embargo, para algunos problemas prácticos se requiere, además de determinar los agrupamientos, conocer las propiedades que describan cómo son dichos agrupamientos. A este problema se le conoce como agrupamiento conceptual.

Existen diversos algoritmos que permiten resolver el problema de agrupamiento conceptual, entre los que se encuentra el algoritmo k-means conceptual, el cual es una versión conceptual del algoritmo k-means; uno de los algoritmos más estudiados y utilizados para resolver el problema de clasificación no supervisada restringida (cuando se especifica *a priori* el número de agrupamientos). La principal característica del algoritmo k-means conceptual es que requiere retículos de generalización para la construcción de los conceptos. En esta tesis se proponen dos algoritmos k-means conceptuales, el primero de ellos es una mejora del algoritmo k-means conceptual y el segundo es un algoritmo k-means conceptual que no requiere retículos de generalización para la construcción de los conceptos.

Finalmente, en esta tesis se proponen dos algoritmos conceptuales difusos, los cuales son versiones difusas de los algoritmos conceptuales duros propuestos.

Palabras Clave: Agrupamiento Conceptual, Agrupamiento Conceptual Difuso, Funciones de Similaridad, Datos Mezclados.

# **1** Introduction

The clustering algorithms determine clusters such that objects in the same cluster are similar among them, while objects in different clusters are less similar. However, there are some situations where, besides determining the clusters, the properties that characterize them are required. This problem is known as conceptual clustering.

The first conceptual clustering algorithms were proposed by Michalski (Michalski and Diday, 1981; Michalski and Stepp, 1983; Stepp and Michalski, 1986) and starting from these, other conceptual clustering algorithms have been developed (Lebowitz, 1986; Hanson, 1990; Fisher, 1990; Gennari et al., 1990; McKusick and Thompson, 1990; Béjar and Cortés, 1992; Ralambondrainy, 1995; Martínez-Trinidad and Sánchez-Díaz, 2001; Pons-Porrata et al., 2002; Seeman and Michalski, 2006). These conceptual clustering algorithms can be divided in two types: restricted and non restricted. The restricted conceptual algorithms are those where the number of clusters, and concepts, to build is specified *a priori*, and usually they require seeds for working; while the non restricted conceptual algorithms are those where the number of clusters is not specified *a priori*. In this thesis, the restricted conceptual clustering problem based on seeds was addressed.

In this thesis, two extensions of the conceptual k-means algorithm (Ralambondrainy, 1995), which allow working with mixed and incomplete data using any object comparison function were proposed. Also, two fuzzy conceptual clustering algorithms, which are fuzzy versions of the proposed conceptual clustering algorithms, were proposed.

# **2** Restricted Conceptual Algorithms

The conceptual k-means algorithm (Ralambondrainy, 1995) is a conceptual version of the k-means algorithm, one of the most studied and used algorithms for solving the clustering problem when the number of clusters is specified *a priori*. The conceptual k-means algorithm consists of two phases: an aggregation phase, where the clusters are built and a characterization phase, where the properties or concepts are generated. This algorithm allows working with objects described by mixed (quantitative and qualitative) features; and it does not allow missing data.

In the aggregation phase, a distance for measuring similarities among objects is defined. The distance function is defined as the sum of the Euclidean distance, for quantitative features; and the Chi-square distance, for the qualitative features. In order to apply the Chi-square distance, a transformation of each qualitative feature into a set of Boolean features, must be done. This codification does not transform the representation space in  $\Re^n$ , where means can be computed, because the 1's y 0's associated to the new features are codes not numbers; therefore, the obtained centroids (means) do not have an interpretation in  $\Re^n$ .

In the characterization phase, a generalization lattice for each feature is needed. For qualitative features, the generalization lattice must be given *a priori*. For quantitative features, a codification into qualitative features is done. The codification function, for each quantitative feature is the following:

$$c(r) = \begin{cases} inf & if \quad r < \mu_x - \sigma_x \\ typical & if \quad \mu_x - \sigma_x \le r \le \mu_x + \sigma_x \\ sup & if \quad \mu_x + \sigma_x < r \end{cases}$$
(1)

where *r* is a value of the feature *x*;  $\mu_x$  is the *mean* of the feature *x* in the cluster  $A_i$  and  $\sigma_x$  is the *standard deviation* of *x* in the cluster  $A_i$ . Using this codification, the following generalization lattice was proposed by Ralambondrainy:



Fig. 1. Generalization lattice for the quantitative features proposed by Ralambondrainy

Before presenting the conceptual clustering algorithms proposed in this thesis, a formal outline of the conceptual clustering problems is given.

### 2.1 Restricted Conceptual Clustering

Let  $X = \{O_1, ..., O_n\}$  be a set of objects. Each object  $O_j$  is described by a set of features  $R = \{x_1, ..., x_m\}$ . Each feature  $x_s$  takes values in a set of admissible values  $D_s$ ,  $x_s(O_j) \in D_s$ , s = 1, ..., m, j = 1, ..., n; with  $x_s(O_j)$  the value of the feature  $x_s$  in the object  $O_j$ . The features can be of any nature (qualitative: Boolean, multi-valued, etc. or quantitative: integer, real). Also, it is assumed that  $D_s$  contains the symbol "?" which denotes missing data; thus, incomplete object descriptions can be considered.

For each feature  $x_s$ , a comparison function  $FC_s : D_s \times D_s \to L_s \ s=1,2,...,m$ , is defined, where  $L_s$  is a completely ordered set. The  $FC_s$  function gives an evaluation of the similarity degree between two values of the feature  $x_s$ . In addition, let  $\Gamma : (D_1 \times ... \times D_m)^2 \to [0,1]$  be a similarity function, which allows evaluating the similarity degree between two object descriptions.

The restricted conceptual clustering problem consists in structuring the objects in k clusters  $\{A_1, ..., A_k\}$ ,  $k \ge 1$ , and generating properties or concepts,  $C_i$ , for characterizing the clusters  $A_i$ , i = 1, ..., k.

A concept  $C_i$  will be represented as a disjunction of predicates  $P = (x_1, a_1) \land \ldots \land (x_m, a_m)$ , with  $x_s \in R$  and  $a_s \in D_s$ . The predicate *P* covers an object  $O_j$  if  $x_s(O_j) = a_s$  or  $a_s$  is more general than  $x_s(O_j)$  according to the generalization lattice of  $x_s$ ,  $s = 1, \ldots, m$ . Also, a concept  $C_i$  covers an object  $O_j$  if at least one predicate *P* in the concept  $C_i$  covers the object  $O_j$ .

A concept  $C_i$  for the cluster  $A_i$  must satisfy that if the object  $O_j$  belongs to the cluster  $A_i$  then the object  $O_j$  should be covered by the concept  $C_i$ ; and if the object  $O_j$  does not belong to the cluster  $A_i$  then the object  $O_j$  should not be covered by the concept  $C_i$ .

### **2.2 Quality Function**

For comparing the algorithms that solve the conceptual clustering problem, a function for evaluating the quality of the concepts is required. In order to measure this quality, some characteristics of the concepts that can be taken into account are: the percentage of objects belonging to a cluster that are covered by the concept, the number of objects outside the cluster covered by the concept, the size of the concepts, or the simplicity of the concepts.

Ralambondrainy (1995) proposed to take the percentage of objects belonging to the cluster that are covered by the concept as quality measure. However, it is also necessary to take into account the objects outside the cluster that are covered by the concept; because this allows to evaluate not only how the concepts characterize the clusters, but also how much the concepts differentiate objects of a cluster from objects in other clusters.

The quality function that we propose in this thesis takes into account the number of objects in a cluster covered by the concept (examples) as well as the number of objects outside the cluster covered by the concept (counterexamples). A concept will have better quality if it recognizes more examples and less counterexamples. The maximum quality is reached when the concepts cover to all the objects in their clusters and any object outside of them. The proposed quality function is the following:

$$quality(C_1, \dots, C_k) = \frac{1}{k} \sum_{i=1}^k \frac{examples(C_i)}{|A_i| + counterexamples(C_i)}$$
(2)

where:

kis the number of clusters.C\_iis the concept associated to the cluster  $A_i$ , i = 1,...,k.examples(C\_i)is the number of objects in the cluster  $A_i$  covered by the concept  $C_i$ .counterexamples(C\_i)is the number of objects outside the cluster  $A_i$  covered by the concept  $C_i$ .

This function takes higher values if the number of covered examples increases and the number of covered counterexamples decreases. This function takes 1.0 when the concept  $C_i$  covers all the objects in the cluster  $A_i$  and it does not cover any object outside of  $A_i$ .

# 2.3 Conceptual K-means Algorithm based on Similarity Functions

The first algorithm proposed in this thesis is the conceptual k-means algorithm based on similarity functions (CKMSF), which is a modification of the conceptual k-means algorithm (CKM) (Ralambondrainy, 1995). The CKMSF algorithm consists of two phases: a clustering phase and a characterization phase.

## 2.3.1 Clustering Phase

In this phase, we propose to use the k-means with similarity functions algorithm (KMSF) (García-Serrano and Martínez-Trinidad, 1999) for building the clusters. This algorithm, opposite to the CKM algorithm, allows using any comparison function to compare feature values and any similarity function to compare objects. Also, in the KMSF algorithm objects of the sample are selected as centroids instead of using means.

### 2.3.2 Characterization Phase

In this phase, a generalization lattice for each feature is required. The generalization lattices for qualitative features must be given *a priori* by the user; while, for quantitative features, the same codification than CKM and the generalization lattice proposed by Pons-Porrata (1999) (Figure 2) were used.





First, an initial predicate  $P = (x_1, a_1) \land \ldots \land (x_m, a_m)$  for each object  $O_j \in A_i, j = 1, \ldots, |A_i|$  is built, where  $a_s$  is the value of the feature  $x_s$  in the object  $O_j$ .

Starting from these predicates and based on the generalization lattices generalized predicates are generated. Two predicates  $P_1 = (x_1, a_1) \land \ldots \land (x_m, a_m)$  and  $P_2 = (x_1, b_1) \land \ldots \land (x_m, b_m)$  will be generalized if, for each feature  $x_s$ ,  $s = 1, \ldots, m$ , the values  $a_s$  and  $b_s$  are equal or they can be generalized in the generalization lattice defined for the feature  $x_s$ . If the values  $a_s$  and  $b_s$  can not be generalized, then  $P_1$  and  $P_2$  will not be generalized.

The generalization of the values  $a_s$  and  $b_s$  of each feature  $x_s$  is made as follows: if the values  $a_s$  and  $b_s$  are equal then, the generalized predicate will take this value for the feature  $x_s$ ; if the values are different then the value for the feature  $x_s$  in the generalized predicate will be the generalization of  $a_s$  and  $b_s$  given by the lattice. If a value is more

general than the other then the value for the feature  $x_s$  that the generalized predicate will take is the most general value of them.

A generalized predicate is stored if it is  $\alpha$ -discriminating (the number of objects outside of  $A_i$  covered by the predicate is smaller or equal than  $\alpha$ ) and  $\beta$ -characterizing (the number of objects in  $A_i$  covered by the predicate is greater o equal than  $\beta$ ), in other case it is eliminated. If a new predicate is stored then the predicates, starting from which this predicate was generated, are eliminated. This generalization process is repeated until no more generalized predicates can be generated.

The obtained set of predicates can contain predicates that recognize the same objects; therefore, this set can be reduced (eliminating those predicates recognizing the same objects than another predicate). This reduction is made using the strategy proposed by Ralambondrainy (1995) which works as follows: the predicates are descendently ordered according to the number of objects that each one covers. The first predicate is stored. For the remaining predicates, if a predicate covers any object not covered by the stored predicates then this predicate is added to the concept; otherwise, it is eliminated. Finally, the concept will be formed by the disjunction of the stored predicates.

In a generalization lattice the symbol \* indicates that the feature can take any value; therefore, in order to simplify a concept we can eliminate from the predicates those features that contain \*; which are not useful as descriptors for the concept.

The main problem of using generalization lattices is that they could be difficult to define; moreover, there are not automatic methods to build these lattices, therefore this task must be done by the user. For this reason, in the next section, we propose a new k-means conceptual algorithm that does not depend on generalization lattices for the construction of the concepts.

# 2.4 Conceptual K-means Algorithm based on Complex Features

In this section, a conceptual k-means algorithm based on complex features (CKMCF) which, as CKM and CKMSF algorithms, has a clustering phase and a characterization phase is proposed.

### 2.4.1 Clustering Phase

In this phase, as in the CKMSF, we use the k-means with similarity functions algorithm for building the clusters.

### 2.4.2 Characterization Phase

The complex features (De-la-Vega-Doria, 1994) are combinations of values for a subset of features such that these values appear in objects of the cluster  $A_i$  and, they do not appear in objects of other clusters. These values characterize objects in the cluster  $A_i$  and they do not characterize objects outside of  $A_i$ . Therefore, the complex features can be used for generating concepts. A complex feature is defined as follows:

**Definition 2.1:** Let  $\Omega = \{x_{s_1}, ..., x_{s_p}\}$  be a set of features and let  $(a_1, ..., a_p)$  be values associated to the features  $x_{s_1}, ..., x_{s_p}$  taken from an object of the cluster  $A_i$ , then  $\{x_{s_1}, ..., x_{s_p}\}$ - $(a_1, ..., a_p)$  is a **complex feature** (De-la-Vega-Doria, 1994) of the cluster  $A_i$ , if and only if:

1994) of the cluster  $A_i$ , if and only if: 1)  $\sum_{O_j \in A_i} \Gamma(\Omega O_j, (a_1, ..., a_p)) \ge \beta_i$ 2)  $\sum_{\Omega \neq A} \Gamma(\Omega O_j, (a_1, ..., a_p)) < \lambda_i$ 

where  $\Omega O_j$  is the subdescription of the object  $O_j$  taking into account only the features of  $\Omega$ ;  $\beta_i$  is the minimum similarity that the objects of the cluster  $A_i$  should have with the subdescription  $(a_1, ..., a_p)$  and  $\lambda_i$  is the maximum similarity that the objects outside the cluster should have with  $(a_1, ..., a_p)$ .

In order to obtain the complex features, subsets of features  $\Omega$  that indicate the subdescriptions of the objects where the complex features will be searched; these subsets are called support sets. The following support sets are used for the CKMCF algorithm:

- 1. Γ-discriminating support sets (Alba-Cabrera, 1997); which are subsets of features such that the difference among objects from different clusters is greater than the difference considering all the features.
- 2. Γ-characterizing support sets (Alba-Cabrera, 1997); which are subsets of features such that the similarity among objects in the same cluster is greater than the similarity considering all the features.
- 3.  $\Gamma$ -testors support sets (Alba-Cabrera, 1997); which are subsets of features satisfying the properties  $\Gamma$ -discriminating and  $\Gamma$ -characterizing at the same time.

The support sets are obtained through a genetic algorithm, which is described in (Guevara-Cruz, 2004) and the complex features are computed using these support sets and verifying the definition 2.1.

In order to generate the concepts, a predicate P is associated to each complex feature. The predicate P is a conjunction of feature values, where the features that appear in the complex feature take the value  $a_s$  and the features that do not appear in the complex feature take the value \*. The symbol \* means "any value is possible".

The set of predicates obtained from the complex features can contain predicates that recognize the same objects; therefore, this set of predicates can be reduced (eliminating predicates that recognize the same objects than another predicate). This reduction is made using the same strategy used for reducing the predicates in the CKMSF algorithm.

### **2.5 Experimental Results**

In order to illustrate the performance of the proposed algorithms (Sections 2.3 and 2.4), the results obtained by applying the CKMSF and CKMCF algorithms on different databases are presented in this section. The databases used for the experiments were taken from the UCI databases repository (Blake et al., 1998). For these experiments, we ignored the labels of the classes. In addition, a comparison among our algorithms and the conceptual k-means (CKM) algorithm is shown.

In the experiments, the following similarity function was used:

$$\Gamma(O_p, O_j) = \frac{\sum_{x_s \in \mathcal{R}} FC_s(x_s(O_p), x_s(O_j))}{m}$$

where  $FC_s(x_s(O_p), x_s(O_i))$  is the comparison function used for comparing values of the feature  $x_s$ .

The comparison functions used for the experiments were the following:

1. For quantitative features:

$$FC_{s}(x_{s}(O_{i}), x_{s}(O_{j})) = \begin{cases} 0 & \text{if } x_{s}(O_{i}) = ? \lor x_{s}(O_{j}) = ? \lor |x_{s}(O_{i}) - x_{s}(O_{j})| \ge \sigma \\ 1 & \text{in other case} \end{cases}$$

where  $\sigma$  is the standard deviation of the feature  $x_s$  in the sample. 2. For qualitative features:

$$FC_{s}(x_{s}(O_{i}), x_{s}(O_{j})) = \begin{cases} 0 & \text{if } x_{s}(O_{i}) = ? \lor x_{s}(O_{j}) = ? \lor x_{s}(O_{i}) \neq x_{s}(O_{j}) \\ 1 & \text{in other case} \end{cases}$$

The treatment given, in this thesis, to missing data is the following: when a value of the feature  $x_s$  is missing ("?") then it is considered as different from any other value, even from another missing value.

In Table 1, the quality and the number of predicates of the concepts obtained by each algorithm (CKM, CKMSF and CKMCF) are shown.

In Figure 3 the results of Table 1 are shown in a graph. For the CKMCF algorithm, only the results obtained with the  $\Gamma$ -discriminating support sets, which were the support sets that obtained the best results, are depicted.

In Table 1 and Figure 3, we can observe that, in average, the best quality is obtained with the CKMSF and CKMCF algorithms. In average, the CKMCF algorithm using  $\Gamma$ -discriminating support sets obtained concepts with a slightly lower quality than the quality of concepts obtained by the CKMSF algorithm; however, the CKMCF does not require generalization lattices and it obtains concepts with less predicates.

Databases	CKM Algorithm		CKMSF Algorithm		CKMCF Algorithm						
					Гd		Гс		Γt		
	Quality	# Pred.	Quality	# Pred.	Quality	# Pred.	Quality	# Pred.	Quality	# Pred.	
Diabetes	0.53	261	0.83	218	0.89	44	0.89	44	0.89	44	
Glass	0.54	67	0.89	83	0.66	21	0.66	20	0.66	21	
Iris	0.85	52	0.92	10	0.88	3	0.88	3	0.88	3	
Wine	0.29	47	1.00	40	1.00	30	1.00	27	1.00	29	
Hayes	1.00	18	0.99	17	1.00	13	1.00	13	1.00	13	
Lenses	1.00	5	0.95	8	1.00	8	1.00	8	1.00	8	
Zoo	1.00	9	1.00	14	1.00	21	1.00	17	1.00	19	
Auto-mpg	0.75	164	0.61	136	0.62	43	0.62	43	0.62	43	
Echocardiogram	0.40	43	0.88	89	0.94	48	0.94	40	0.95	53	
Hepatitis	0.53	50	0.99	46	0.98	68	0.92	39	0.99	97	
Import85	0.47	57	0.98	63	0.98	113	0.86	46	0.98	114	
Тае	0.89	30	0.97	71	0.95	40	0.95	40	0.95	40	
Average	0.69	67	0.92	66	0.91	38	0.89	28	0.91	40	

Table 1. Quality and number of predicates of the concepts obtained by the CKM, CKMSF and CKMCF algorithms



**Figure 3.** Quality and number of predicates of the concepts obtained by the CKM, CKMSF and CKMCF (using  $\Gamma$ -discriminating support sets) algorithms

# **3 Fuzzy Conceptual Algorithms**

In some practical problems, to determine the membership degree of an object to a cluster instead of determining only if the object belongs or not to the cluster is required. In addition, to obtain fuzzy concepts that provide us a description of the objects belonging with a certain degree to the clusters is very important. This problem is called Fuzzy Conceptual Clustering.

There are some works where the fuzzy conceptual clustering problem has been faced (Martínez-Trinidad and Ruiz-Shulcloper, 1998; Martínez-Trinidad, 2000; Quan et al., 2004a; Quan et al., 2004b). These works address the problem when the number of clusters is not specified *a priori*. However, there are not algorithms for solving the

restricted fuzzy conceptual clustering problem; i.e., when the number of clusters is specified *a priori*. Therefore, in this thesis two restricted fuzzy conceptual clustering algorithms, which are fuzzy versions of the conceptual algorithms proposed in Section 2 are introduced.

### 3.1 Fuzzy Restricted Conceptual Clustering

The fuzzy restricted conceptual clustering problem is similar to the restricted conceptual clustering problem, but the clusters and the concepts are fuzzy.

The fuzzy restricted conceptual clustering problem consists in structuring the objects in k fuzzy clusters  $\{A_1, \ldots, A_k\}, k > 1$ , and generating fuzzy properties or concepts,  $C_i, i = 1, \ldots, k$ .

In this thesis, a fuzzy predicate will be a pair  $(P, \mu_P)$ , where P is a hard predicate that describe some objects and  $\mu_P$  is a value that will be associated to the objects covered by P, i.e., P describes the objects that belong with degree  $\mu_P$  to the fuzzy cluster  $A_i$ .

The degree in that each object is covered by the concept is determined as follows: If an object  $O_i$  is covered by only one fuzzy predicate  $(P, \mu_P)$  of the concept  $C_i$ , the degree in that the object  $O_i$  is covered by the fuzzy concept  $C_i$ will be the value  $\mu_{P}$ . If the object  $O_i$  is covered by more than one fuzzy predicate of  $C_i$ , the degree in that the object  $O_i$  is covered by the fuzzy concept  $C_i$  will be the maximum of the  $\mu_P$  associated to the predicates that cover  $O_i$ ; on the other hand, if any predicate covers the object  $O_i$ , then the fuzzy concept  $C_i$  covers the object  $O_i$  with degree 0.

### **3.2 Quality Funtion**

A fuzzy concept  $C_i$  for a fuzzy cluster  $A_i$  must satisfy: if the object  $O_i$  belongs with high degree to the fuzzy cluster  $A_i$ then it should be covered with high degree by the concept  $C_i$  and if the object  $O_i$  belongs with low degree to the fuzzy cluster  $A_i$  then it should be covered with low degree by the concept  $C_i$ . Therefore, for evaluating the quality of the concepts obtained by the proposed fuzzy conceptual clustering algorithms, a generalization of the quality function for the hard algorithms (2.2) is defined as follows:

$$quality(C_{1},...,C_{k}) = \frac{1}{k} \sum_{i=1}^{k} \frac{\sum_{O \in A_{C_{i}}} \left(1 - \left|\mu_{A_{i}}(O_{j}) - \mu_{C_{i}}(O_{j})\right|\right)}{\left|A_{C_{i}}\right| + \sum_{O \in A_{C_{i}}} \left|\mu_{A_{i}}(O_{j}) - \mu_{C_{i}}(O_{j})\right|}$$
(3)

 $A_{c_i} = \left\{ O_j \middle| \max_{\substack{p=1,\dots,k}} \left\{ \mu_{A_p} \left( O_j \right) \right\} = \mu_{A_i} \left( O_j \right) \right\}$  is the set of objects that belong more to the cluster  $A_i$  than to other clusters.

k is the number of clusters.  $C_i$  is the concept associated to the cluster  $A_i$ .  $\mu_{A_i}(O_j)$  is the membership degree of the object  $O_j$  to the cluster  $A_i$ .  $\mu_{c}(O_{i})$  is the degree in which the object  $O_{i}$  is covered by the concept  $C_{i}$ .

The function (3.1) takes high values if the difference between the membership degree of the objects to the clusters and the degree in which they are covered by the concepts is small. The function takes 1.0 when the concepts cover all the objects in the same degree that they belong to the cluster.

If the membership degrees are hard (0's y 1's) then this function is the same quality function defined for the hard conceptual clustering problem.

# **3.3 Fuzzy Conceptual K-means Algorithm based on Similarity Functions**

The fuzzy conceptual k-means algorithm based on similarity functions (FCKMSF) is an extension of the conceptual k-means algorithm based on similarity functions (CKMSF). The FCKMSF algorithm consists of two phases: a clustering phase and a characterization phase.

### **3.3.1 Clustering Phase**

In this phase, we propose to use the fuzzy k-means with similarity functions algorithm (FKMSF) (Ayaquica-Martínez and Martínez-Trinidad, 2001) to build the fuzzy clusters. The FKMSF algorithm is a fuzzy version of the KMSF algorithm (García-Serrano and Martínez-Trinidad, 1999), which was used in the clustering phase of the proposed hard algorithms.

#### **3.3.2** Characterization Phase

In this phase, a generalization of the CKMSF characterization phase is proposed. This generalization allows generate fuzzy concepts starting from fuzzy clusters.

It is important to remind that, due to the FCKMSF is based on the KMSF algorithm; a generalization lattice for each feature is required. For qualitative features, the generalization lattice must be given *a priori*, while for quantitative features, the codification function (2.1) and the generalization lattice showed in Figure 2 are used.

In order to build the initial predicates, for each fuzzy cluster  $A_i$ , only the objects that belong more to the cluster  $A_i$  than to other clusters are taken into account. A fuzzy predicate  $(P,\mu_P)$  is associated to each object  $O_j$ . The predicate P is built as in the hard case and  $\mu_P$  takes as value the membership degree of the object  $O_j$  to the cluster  $A_i$ .

Starting from these predicates and based on the generalization lattices generalized fuzzy predicates are generated. Two fuzzy predicates  $(P_1, \mu_{P_1})$  and  $(P_2, \mu_{P_2})$  will be generalized if  $|\mu_{P_1} - \mu_{P_2}| < \varepsilon$ , with  $\varepsilon \in [0,1]$  and  $P_1$  and  $P_2$  can be generalized. Thus, only predicates with similar value of  $\mu_P$  are generalized. The predicate P for the generalized fuzzy predicate, will be the generalization of  $P_1$  and  $P_2$ , and the value of  $\mu_P$  for the generalized fuzzy predicate fuzzy predicate  $P_1$ .

It is important to note that if the value of  $\varepsilon$  is close to 1, then we will obtain fuzzy concepts with low quality, because we allow to generalize fuzzy predicates which represent objects with no similar membership degrees; while if the value of  $\varepsilon$  is close to 0, the fuzzy concepts obtained will have high quality, because we allow to generalize only fuzzy predicates with very similar membership degrees; if  $\varepsilon = 0$  the final fuzzy predicates will be all the initial fuzzy predicates and each predicate will cover only one object.

A generalized fuzzy predicate is stored if it is  $\alpha$ -discriminating (the number of objects outside of  $A_i$  covered by the predicate is smaller or equal than  $\alpha$ ) and  $\beta$ -characterizing (the number of objects in  $A_i$  covered by the predicate is greater o equal than  $\beta$ ), in other case it is eliminated. If a generalized fuzzy predicate is stored then the fuzzy predicates, starting from which this predicate was generated, are eliminated. This generalization process is repeated until no more generalized fuzzy predicates can be generated.

The  $\alpha$ -discriminating and  $\beta$ -characterizing properties are verified as in the hard case; therefore, it is necessary hardening the clusters. In order to harden a cluster  $A_i$ , only the objects that belong more to the cluster  $A_i$  than to other clusters are taken into account.

The obtained set of fuzzy predicates can contain predicates that do not contribute to improve the quality of the concepts; therefore, this set can be reduced. This reduction is made using a generalization of the strategy proposed by Ralambondrainy (1995), which works as follows: the fuzzy predicates are descendently ordered according to  $\mu_P$ . The first predicate is stored. For the remaining predicates, if a predicate improves the quality of the concept (measured with the expression (3.1)), then the predicate is added to the concept; otherwise, it is eliminated. Finally, the concept will be formed by the disjunction of the stored fuzzy predicates.

# 3.4 Fuzzy Conceptual K-means Algorithm based on Complex Features

In this section, a fuzzy version (FCKMCF) of the conceptual k-means algorithm based on complex features (CKMCF) is proposed. The FCKMCF algorithm consists of a clustering phase and a characterization phase.

### 3.4.1 Clustering Phase

In this phase, as in the FCKMSF algorithm, the fuzzy k-means with similarity functions algorithm is used for building the fuzzy clusters.

### **3.4.2 Characterization Phase**

In this phase, for generating the concepts, the fuzzy complex features are used. A fuzzy complex feature is defined as follows:

**Definition 3.1:** Let  $\Omega = \{x_{s_1}, ..., x_{s_p}\}$  be a set of features and let  $(a_1, ..., a_p)$  be values associated to the features  $x_{s_1}, ..., x_{s_p}$  taken from an object of the cluster  $A_i$ , then  $\{x_{s_1}, ..., x_{s_p}\}$ - $(a_1, ..., a_p)$  is a *fuzzy complex feature* (Dela Vaga Daria (1004) of the cluster  $A_i$  if and only if

la-Vega-Doria, 1994) of the cluster  $A_i$ , if and only if: 1)  $\sum_{O_j \in X} \left[ \Gamma(\Omega O_j, (a_1, ..., a_p)) \mu_{A_i}(O_j) \right] \ge \beta_i$ 2)  $\sum_{O_j \in X} \left[ \Gamma(\Omega O_j, (a_1, ..., a_p)) (1 - \mu_{A_i}(O_j)) \right] < \lambda_i$ 

where  $\mu_{A_i}(O_j)$  is the membership degree of  $O_j$  to the cluster  $A_i$ ;  $\Omega O_j$ ,  $\beta_i$  y  $\lambda_i$  are defined in the same way as in the hard case.

In order to obtain the fuzzy complex features, support sets are needed. In this thesis, besides the  $\Gamma$ discriminating,  $\Gamma$ -characterizing and  $\Gamma$ -testors, the fuzzy  $\Phi$ -testors are used. The  $\Gamma$ -discriminating,  $\Gamma$ -characterizing and  $\Gamma$ -testors support sets can be obtained only for hard clusters; in a similar way for evaluating the  $\alpha$ -discriminating and  $\beta$ -characterizing properties the clusters were hardening. In order to calculate the  $\Gamma$ -discriminating,  $\Gamma$ characterizing and  $\Gamma$ -testors support sets a genetic algorithm, which is described in (Guevara-Cruz, 2004) was used; and for calculating the fuzzy  $\Phi$ -testors the genetic algorithm proposed by Santos-Gordillo et al. (2003) was used.

In order to generate the concepts, a fuzzy predicate  $(P,\mu_P)$  is associated to each complex feature. The predicate *P* is built as in the hard case and the value of  $\mu_P$  is the average of the membership degrees of the objects covered by the predicate *P*.

The set of fuzzy predicates obtained from the complex features can contain predicates that do not contribute to improve the quality of the concepts. Thus, this set of predicates can be reduced using the same strategy used for reducing the predicates in the FCKMSF algorithm.

# **3.5 Experimental Results**

In order to show the performance of the proposed algorithms (Sections 3.3 and 3.4), in this section the results obtained by applying the FCKMSF and FCKMCF algorithms on different databases are presented. These databases are the same that in the hard case. Also, the similarity function and the comparison functions are the same that in the hard case.

For the fuzzy case, the FCKMSF and FCKMCF algorithms were compared only between them because there are not restricted fuzzy conceptual algorithms for comparing with.

In Table 2 the quality and the number of predicates of the concepts obtained by the FCKMSF and FCKMCF algorithms are shown.

Databases	FCKMSF Algorithm		FCKMCF Algorithm								
			Гd		Гс		Γt		Φt		
	Quality	# Pred.	Quality	# Pred.	Quality	# Pred.	Quality	# Pred.	Quality	# Pred.	
Diabetes	0.66	230	0.68	72	0.68	72	0.68	72	0.70	105	
Glass	0.69	69	0.65	21	0.65	21	0.65	21	0.68	40	
Iris	0.78	37	0.75	3	0.75	3	0.75	3	0.78	10	
Wine	0.62	99	0.57	99	0.57	94	0.57	112	0.60	99	
Hayes	0.71	66	0.63	23	0.63	23	0.63	23	0.65	25	
Lenses	0.77	11	0.66	14	0.66	14	0.66	14	0.70	11	
Zoo	0.64	41	0.59	17	0.50	13	0.58	15	0.60	22	
Auto-mpg	0.60	96	0.72	22	0.72	22	0.72	22	0.75	60	
Echocardiogram	0.64	84	0.57	58	0.57	58	0.56	70	0.63	70	
Hepatitis	0.74	43	0.45	40	0.58	73	0.48	49	0.62	60	
Import85	0.60	112	0.45	18	0.50	37	0.47	31	0.58	90	
Тае	0.72	96	0.52	21	0.52	21	0.52	21	0.60	50	
Average	0.68	82	0.60	34	0.61	38	0.61	38	0.66	54	

Table 2. Quality and number of fuzzy predicates of the concepts obtained by the FCKMSF and FCKMCF algorithms

In Figure 4, the results of Table 2 are shown in a graph. For the FCKMCF algorithm only the results obtained with the  $\Phi$ -testors support sets, which were the support sets that obtained the best results, are depicted.



**Fig. 4.** Quality and number of fuzzy predicates of the concepts obtained by the FCKMSF and FCKMCF (with Φ-testors support sets) algorithms

In Table 2 and Figure 4, we can observe that, the FCKMCF algorithm using  $\Phi$ -testors support sets obtained, in average, concepts with a slightly lower quality than the quality of the concepts obtained by the FCKMSF algorithm; however, the FCKMCF does not require generalization lattices and it obtains concepts with less predicates.

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# **4** Conclusions and Future Work

# 4.1 Conclusions

In this thesis, two restricted conceptual clustering algorithms (CKMSF and CKMCF) and fuzzy versions of them (FCKMSF and FCKMCF) were proposed.

We observed, from the experimentation, that the CKMSF and CKMCF algorithms obtained concepts with better quality than those obtained by the CKM algorithm. Also, the CKMCF algorithm generated concepts with less number of predicates than those obtained by the CKM and CKMSF algorithms.

We can conclude that the CKMCF algorithm is a good alternative for solving restricted conceptual clustering problems when the objects are described by mixed and missing data. On the other hand, when the generalization lattices are known, the CKMSF algorithm is a good alternative for solving this kind of problems.

In the experimentation with the proposed fuzzy conceptual clustering algorithms we observed that the FCKMCF algorithm using  $\Phi$ -testors support sets obtained, in average, concepts with a slightly lower quality than the quality of the concepts obtained by the FCKMSF algorithm; however, The FCKMCF algorithm does not require generalization lattices and it obtains concepts with less number of predicates.

Finally, we can conclude that the FCKMSF and FCKMCF algorithms are a first approximation for solving fuzzy restricted conceptual clustering problems where the objects are described by mixed and missing data.

# 4.2 Future Work

Based on the experimental results we observed that the proposed algorithms obtain concepts with good quality; nevertheless, these qualities can be improved. For that reason, we propose to find new strategies, in the characterization phase, for generating better concepts.

The proposed function for evaluating the quality of the concepts takes into account only the number of objects covered by the concepts, without taking into account their size. As future work we propose to define a quality function that takes into account both characteristics.

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Irene Olaya Ayaquica Martínez received her BS degree in Computer Science from the Computer Science School of the Autonomous University of Puebla (BUAP), Mexico in 1998; her MSc degree in Computer Science from the Center for Computing Research of the National Polytechnic Institute (CIC, IPN), Mexico in 2002; and her PhD degree in Computer Science from the National Institute of Astrophysics, Optics and Electronics (INAOE), Mexico in 2007. Her research interests include: Logical Combinatorial Pattern Recognition, Clustering, Fuzzy Clustering, Conceptual Clustering and Fuzzy Conceptual Clustering.



José Francisco Martínez Trinidad received his B.S. degree in Computer Science from Physics and Mathematics School of the Autonomous University of Puebla (BUAP), Mexico in 1995, his M.Sc. degree in Computer Science from the faculty of Computers Science of the Autonomous University of Puebla, Mexico in 1997 and his Ph.D. degree in the Center for Computing Research of the National Polytechnic Institute (CIC, IPN), Mexico in 2000. Professor Martinez-Trinidad edited/authored four books and over fifty papers, on subjects related to Pattern Recognition.



Jesús Ariel Carrasco Ochoa received his PhD degree in Computer Science form the Center for Computing Research of the National Polytechnic Institute (CIC-IPN), Mexico, in 2001. He works as full time researcher at the National Institute for Astrophysics, Optics and Electronics of Mexico. His current research interests include, Logical Combinatorial Pattern Recognition, Testor Theory, Feature and Prototype Selection, and Clustering.